# ARTIFICIAL INTELLIGENCE BASED TECHNIQUE FOR SINGLE LINE TO GROUND FAULT IDENTIFICATION AND ARC EXTINGUISHMENT

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A thesis submitted in fulfilment of the requirement for the award of the Doctor of Philosophy in Electrical Engineering

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> > MARCH 2023

I would like to dedicate my work to my husband Abid Musslem Abbas because of his patience, love, and care during my PhD journey. Also, I dedicate it to my sons: Dr. Ahmed, Dr. Hassanain, and Dr. Abbas, due to their support and love, which is always with me to achieve this milestone.



### ACKNOWLEDGEMENT

Many thanks to Allah the Almighty, who gave me the strength and wisdom to complete this work. I would like to thank my supervisor, Assoc. Prof. Ir. Dr. Dur Muhammad Soomro for support and help throughout my research work by providing effective advice all the time. Also, I would also like to thank all the administration staff of postgraduate at the Faculty of Electrical and Electronic Engineering for helping me all the time.

### ABSTRACT

Single line-to-ground fault (SLGF) is the most common fault in the distribution network of the power system (PS). The disadvantage of this fault is to cause residual current  $(I_{res})$  initiating an electrical arc along with a high voltage (HV) of the order of three times the rated voltage in other healthy phases. This HV is caused by the capacitive currents  $(I_c)$ , which is very dangerous for the insulation of cables as well as the PS appliances, including personnel and protection systems. To solve  $I_{res}$  conventionally, Peterson Coil (PC) has been used by connecting it with the neutral point, which reduces it and extinguishes the electric arc, but both not fully, i.e., still some value of fault current  $(I_{fault})$  remains. If it is not reduced to an extent, initiating the arc again can be more dangerous to the PS. Among them, some researchers were focused on SLGF detection, and only a few were interested in studying the extinguishing time of the electric arc. These solutions are incompatible with the requirement of developing technology due to the increased demand for efficiency, economy, reliability, quality, and electrical energy consumption. Therefore, they were replaced with the advanced/ heuristics methods/algorithms to optimize the results of detection of SLGF and time of extinguishing the electric arc by making PC adaptive (APC). These methods include Fuzzy Logic (FL), Neural Networks (NN), Neural Fuzzy Networks (NFN), etc. Most of the cited heuristic methods application is on reducing the  $I_{fault}$  while some of them worked for the detection of SLGF, but no one considered the time of extinguishing the electric arc to minimize and optimize the inductance of the PC for the parallel resonance. Therefore, this research considers the parameters of time of detection of SLGF, reduction of  $I_{res}$ , reduction of time of extinguishing the electric arc, sensing & activation of protection devices for the  $I_{fault}/I_{res}$  when it is less than 20% using different proposed algorithm-based techniques such as Fuzzy Logic Control (FLC), hybrid Artificial Neural with Fuzzy Inference System (ANFIS), and hybrid Artificial Bee Colony with Neural Network (ABCNN) using MATLAB 2010a. Furthermore, ABCNN is the novel technique introduced in this thesis.

### ABSTRAK

Sesar talian ke tanah tunggal (SLGF) ialah kerosakan yang paling biasa dalam rangkaian pengedaran sistem kuasa (PS). Kelemahan kerosakan ini adalah menyebabkan arus sisa  $(I_{res})$  memulakan arka elektrik bersama-sama dengan voltan tinggi (HV) daripada susunan tiga kali voltan terkadar dalam fasa sihat yang lain. HV ini disebabkan oleh arus kapasitif  $(I_c)$ . yang sangat berbahaya untuk penebat kabel serta peralatan PS, termasuk kakitangan dan sistem perlindungan. Untuk menyelesaikan I<sub>res</sub> secara konvensional, Peterson Coil (PC) telah digunakan dengan menyambungkannya dengan titik neutral, yang mengurangkannya dan memadamkan arka elektrik, tetapi kedua-duanya tidak sepenuhnya, iaitu, masih terdapat beberapa nilai arus kerosakan  $(I_{fault})$ . Jika ia tidak dikurangkan ke satu tahap, memulakan arka sekali lagi boleh menjadilebih berbahaya kepada PS. Ramai penyelidik berminat untuk mengkaji pengesanan SLGF dan memadamkan arka elektrik. beberapa penyelidik tertumpu pada pengesanan SLGF, dan hanya sebilangan kecil yang berminat untuk mengkaji masa pemadaman arka elektrik. Penyelesaian ini tidak serasi dengan keperluan untuk membangunkan teknologi disebabkan oleh peningkatan permintaan untuk kecekapan, ekonomi, kebolehpercayaan, kualiti dan penggunaan tenaga elektrik. Oleh itu, ia digantikan dengan kaedah/algoritma lanjutan/heuristik untuk mengoptimumkan hasil pengesanan SLGF dan masa pemadaman arka elektrik dengan membuat penyesuaian PC (APC). Kaedah-kaedah ini termasuk Logik Kabur (FL), Rangkaian Neural (NN), Rangkaian Kabur Neural (NFN), dll. Kebanyakan aplikasi kaedah heuristik yang dipetik adalah untuk mengurangkan  $I_{fault}$  manakala sebahagian daripadanya berfungsi untuk pengesanan SLGF, tiada siapa yang mempertimbangkan masa memadamkan arka elektrik untuk meminimumkan dan mengoptimumkan kearuhan PC untuk resonans selari. Oleh itu, penyelidikan ini mempertimbangkan parameter pengesanan SLGF, pengurangan  $I_{res}$ , pengurangan masa pemadaman arka elektrik, penderiaan & pengaktifan peranti perlindungan untuk  $I_{fault}/I_{res}$  apabila ia kurang daripada 20% menggunakan teknik berasaskan algoritma yang berbeza. seperti

Kawalan Logik Fuzzy (FLC), Neural Tiruan hibrid dengan Sistem Inferens Kabur (ANFIS), dan Koloni Lebah Buatan hibrid dengan Rangkaian Neural (ABCNN) menggunakan MATLAB 2010a. Tambahan pula, ABCNN merupakan teknik novel yang diperkenalkan dalam tesis ini.

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# LIST OF SYMBOLS AND ABBREVIATIONS

$C_{LN}$	-	Line-to-neutral capacitance
$C_{SG}$	-	Capacitance between S-phase and ground
C <sub>0</sub>	-	Zero-sequence capacitance
$C_g$	-	Ground capacitance
$C_R$	-	Capacitance of R-phase
$C_S$	-	Capacitance of S-phase
$Fe_1$	-	Feeder Number 1
Fe <sub>2</sub>	-	Feeder Number 2
$Fe_3$	-	Feeder Number 3
Ι	-	Feeder Number 3 Current Zero sequence Current in a PC
I <sub>0P</sub>	-	Zero sequence Current in a PC
$I_2$	-	Negative Sequence Current
I <sub>C</sub>	-	Charging Current
I <sub>CF</sub>	-	Charging current in a neutral point
I <sub>cs</sub>	J	Charging current in the S-phase
I <sub>CR</sub>	-	Charging current in the R-phase
I <sub>fault</sub>	-	Fault current
$I_L$	-	Inductive current
I <sub>0</sub>	-	Zero-sequence current in the network
$I_N$	-	Neutral point current
I <sub>Rated</sub>	-	Rated current
I <sub>res</sub>	-	Residual Current
I <sub>adp</sub>	-	Adaptive current
i <sub>1RST</sub>	-	Currents of R, S, T- phases in feeder 1
i <sub>2RST</sub>	-	Currents of R, S, T -phases in feeder 2
i <sub>3FR</sub>	-	Fault current in R-phase in feeder 3
i <sub>3RST</sub>	-	Currents of R, S, T- phases in feeder 3

$L_{PC}$ or $L$	-	Inductor (PC)
V	-	Voltage
$V_n$	-	Voltage at the neutral point
$V_{Rated}$	-	Rated Voltage
$V_0$	-	Zero sequence voltage
$V_L$	-	Line voltage
$V_N$	-	Voltage at a neutral point
$V_S$	-	Phase voltage
$Y_g$	-	Star connection with the grounding
$Y_n$	-	Star connection with neutral without grounding
$Z_L$	-	Impedance of PC
ABC	-	Artificial Bee Colony
AG	-	Arcing Ground
ANN	-	Artificial Neural Network
ASC	-	Arc Suppression Coil
APFM	-	Arc Suppression Coil Amplitude-polarity feature matrix Adaptive Petersen Coil
APC	-	Adaptive Petersen Coil
AFLC	-	Adaptive Fuzzy Logic Control
AANFIS	-	Adaptive Neural Fuzzy Inference System
AABCNN	-	Adaptive Artificial Bee Colony with Neural Network
BDT	DD	Big Data Theory
BST	-	Bayesian Selectivity Technique
CAET	-	Correlation Analysis of Extension Theory
CoG	-	Centre of Gravity
CT	-	Current Sensor
DLGF	-	Double Line To Ground Fault
DWPT	-	Discrete Wavelet Packet Transform
DWT	-	Discrete Wavelet Transform
DSP	-	Digital Signal Processing
DQ	-	Direct Quadrature
EA	-	Electric Arc
EMTP	-	Electromagnetic Transients Program
FL	-	Fuzzy Logic

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Fuzzy Subtractive Clustering and Wavelet Transform	

- *FIS* Fuzzy Inference System
- *FLS* Fuzzy Logic System
- *GS* Grounding System
- *GFC* Ground Fault Current
- *GRD* Grey Relation Degree
- HV High Voltage

FSCWT

- *HIF* High Impedance Fault
- *LLF* Line To Line Fault
- *TPGF* Three-Phase To Ground Fault
- *TFM* Time-Frequency Matrix
- *TGs* Traditional Grids
- MISO Multi-Input-Single-Output
- MIMO Multi-Input-Multi-Output
- *MVDN* Medium Voltage Distribution Network
- *MLP* Multi-Layer Perceptron
- *NFN* Neural-Fuzzy Network
- NN Neural Network
- *NNWT* Neural Network and Wavelet Transform
  - *OV* Over Voltage
- PC Petersen Coil
- *PS* Power System
- *PM* Prony's Method
- PSCAD Power Systems Computer-Aided Design
- *PDM* Polarity Distribution Matrix
- *RGS* Resonant Grounding System
- *RG* Resonant Grounding
- *LA* learning algorithm
- *RS232* Cable (Recommended Serial Connection)
- *SCI* Serial Connection Interface
- SLGF Single Line Ground Fault
- *SVM* Support Vector Machines
- *TFM* Time-Frequency Matrix

- *TI* Texas Instruments
- *WT* Wavelet Transform
- *WFNN* Wavelet With a Fuzzy Neural Network

PERPUSTAKAAN TUNKU TUN AMINAH

## LIST OF APPENDICES

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### **CHAPTER 1**

### **INTRODUCTION**

### 1.1 Research Background

Rapid urbanization and development are causing an increase in the consumption of electricity. The electricity supply through the grid system is facing many challenges due to numerous faults. Some faults are short-term faults (STF), while others are considered long-term faults (LTF). Typically, STF occurs due to failure of the conductor, fuse, circuit breaker, and protection relays. These faults are easy to repair within short intervals. Whereas LTF mainly occurs due to the failure of main power lines or other massive breakups of electricity supply equipment, therefore it is hazardous and takes time to get fixed. It causes a short circuit and disturbs the electricity supply. There are numerous reasons for LTF in the grid system. The common sources of a short circuit are the contact between two lines through metal, trees, wind, birds, and animals.



Four main faults in a distribution system, namely single line-to-ground fault (SLGF), line-to-line fault (LLF), double line-to-ground fault (DLGF), and three-phase to-ground fault (TPGF), comes under the category of LTF [1]. About 70% of the total faults in the distribution system are SLGF. During this fault, an electrical arc appears in the faulted phase and high voltage (HV) between two healthy phases. It is of the order of three times the phase-to-phase voltage, making network isolators risky to operate [2]. To avoid the leakage of unbalanced capacitance (C) charging current ( $I_c$ ) at fault position due to SLGF, the neutral point must be grounded so that the unwanted residual current ( $I_{res}$ ) flows to the ground. Though the application of classical Peterson Coil (PC) inductance (L) is a very old technique.

Even then, it is now being used in between the neutral point and the ground to reduce/compensate/control the  $I_{res}$  and extinguish the electrical arc to make the distribution network safer [3, 4]. The current (*I*) flowing through L is called Inductive Current ( $I_L$ ).

Normally, the  $I_{res}$  is as of the amplitude of 3 times the rated current  $(I_{Rated})$ also known as fault current  $(I_{fault})$ . For this, in practice, the protection system works at the minimum threshold of  $\geq 20\%$  above the  $I_{Rated}$  counting it as a  $I_{fault}$  [2,5,6]. If the amplitude of  $I_{res}$  is >100% and <120% (not detected by the protection system), it may cause HV in healthy phases and restriking electric arc. It needs to be controlled otherwise, not only damage to the equipment of the power station but also hazardous to the personnel. This is of great concern and is the focus of this research. The controlled *I* in this range is known as the adaptive current  $(I_{adap})$ . Based on the foregoing problem, this study seeks to address the issues raised by investigating aspects of SLGF detection and extinguishing electric arcs in a Medium Voltage Distribution Network (MVDN).

For controlling this  $I_{adap}$ , certain traditional methods, such as Wavelet Transform (WT), Prony's Method (PM), Time-Frequency Method (TFM), Big Data Theory (BDT), Grey Relation Degree (GRD), Correlation Analysis of Extension Theory (CAET), Bayesian Selectivity Technique (BST) were used at the initial stage and have become obsolete with the time period [5]. One of the reasons is the incompatibility with future demand, especially when it comes to detecting distribution network faults.

Different researchers have used different heuristic methods for the reduction of electric arcs. Such methods include Fuzzy Logic (FL), Neural Network (NN), and WT [4, 6, 7, 8, 9]. Among these methods, the NN possesses better system reliability and provides better network distribution results and safety for devices and personnel [10]. Moreover, [11, 12, 13, 14] identified the nature of faults (SLGF or LLGF), while [15] improved it and used the combination of a fuzzy-neural method to improve the fault detection and problem fixing analysis.

PC can be used with a combination of optimization techniques [16] to tune the *L* called adaptive PC (APC). In modern technology, the use of Artificial Intelligence (AI) seems to benefit in detecting the fault and thus reducing the electric arc. Therefore, the heuristic methods like Fuzzy Logic Control (FLC), hybrid Artificial



Neural Fuzzy Inference System (ANFIS), and hybrid Artificial Bee Colony Neural Network (ABCNN) can be used to make the APC. Therefore, the techniques applied will be known as adaptive FLC, ANFIS, and ABCNN and abbreviated as AFLC, AANFIS, and AABCNN, respectively.

The proposed techniques of AFLC, AANFIS, and novel AABCNN are used to identify the range of the suggested  $I_{res}/I_{fault}$ . For this purpose, a technique of parallel resonance was utilized to compensate for the  $I_L = I_C$ . Series resonance is not used for such compensation because it produces dangerous overvoltage (OV), the  $V_S$  between lines a bit non-symmetrical and creates a zero-sequence voltage ( $V_0$ ) during a typical operation case [17, 18, 19, 20]. Moreover, to the best of the knowledge of the writer of this thesis, due to its adverse effects, none of the researchers had ever used it.

The developed algorithms of the proposed techniques were Simulated in Matlab on the real test case developed in Simulink. The real test case is a real MVDN called Babylon, Middle Euphrates power station of Iraq. Furthermore, for the validation purpose, the optimized results of the novel AABCNN were practically simulated on a power distribution simulator lying in the power laboratory of the Electrical Engineering department at the University of Babylon/ Iraq using online Texas Instrument Chip (eZdsp F28335) and compared with other researches as well. Besides, the results of AFLC and AANFIS were also compared with other research in terms of the time of SLGF detection and the time of extinguishing the electricity.



### 1.2 **Problem Statement**

It is the responsibility of the electric power utility/supplier to maintain the reliability of the power supply to the consumer. One or the other way, the overhead as well as underground PS faces challenges of faults and, consequently, power interruption [21, 22]. The causes of it can be natural as well as human error. Most of the faults are of SLGF in distribution networks [2]. One of the problems is HV in healthy phases due to  $I_{res}$  causing conductor insulators to fail, as well as other short circuits, posing a severe threat to the electrical distribution network [23]. This condition risks the network's operation devices, equipment, and technical personnel. Therefore, they need accurate, fast, dependable protection devices to supply electricity efficiently [24]. As discussed before, the protection system fails to work for the  $I_{fault}$  below the threshold of 20%, which makes hazardous conditions (in terms of V rise to three times between two healthy phases and restricting the electrical arc) for the PS if undetected and left unattended. Though a classical PC is still used to control the V at the neutral point  $(V_n)$  to make the system stable and extinguish the electric arc, it cannot detect the SLGF. Therefore, multiple heuristic methods, like FL, NN, WT, etc., are used to tune it in parallel resonance (called adaptive) for the detection of SLGF. Consequently, in this research, AFLC, AANFIS, and a novel AABCNN are used to tune PCs. Such algorithms were developed to quickly detect the SLGF and to optimize and reduce the time of extinguishing an electric arc. It was simulated using MATLAB 2010a.

A test case of a real MVDN (33 kV) was used in this respect. An  $I_L$  is applied to compensate for the resonance of the PC at the SLGF point. A typical challenging issue on which all this research is based was to observe the optimum value of L to tune the PC, which was solved through an experimental setup in the PS laboratory, department of electrical engineering at Babylon University, Iraq. A parallel resonance condition was chosen to ensure that the greater  $V, V_n$  is averted. For complete parallel resonance of the network, PC was made to be comparable to ground capacitance  $(C_q)$ Research Objectives that entirely compensates the  $I_{fault}$ .

### 1.3

To achieve the main objective of this research, the detection of SLGF and optimizing the time of extinguishing the electric arc were studied in this research. For this, the behaviour of SLGF in MVDN was examined. Following are the sub-objectives which were set to obtain the main task.

- (i) To develop a detection technique of  $I_{res} < 20$  % of the  $I_{Rated}$  using AFLC, AANFIS, and AABCNN in SLGF.
- (ii) To formulate a new optimization technique using the algorithm to reduce the time for the self-extinguishing of the electric arc.
- (iii) To validate APC in parallel resonance technique, an offline AABCNN was compared with the results of practical/online AABCNN using Texas Instrument chip (eZdsp F28335) in MATLAB.

For the detection of SLGF and optimizing the time of extinguishing the electric arc, the following scope is set for this research.

- (i) A real MVDN test case of 11 kV, 4-busbar at Babylon, Meddle Euphrates power station of Iraq, was selected for the simulation to achieve the set objectives.
- The  $I_{rated}$  is set to 100 A for the purpose of the safety of equipment and (ii) personnel.
- (iii) The SLGF was applied on the R phase in feeder 3  $Fe_3$  only.
- The selected C, i.e., 0.5, 1.0, 1.5, 2.5, 3.5, 5.0  $\mu$ F were used for the (iv) compensation of various turns of L with respect to the  $V_n$  and  $I_{fault}$ .
- (v) The selected tapings of PC, i.e., 180, 254, 350, 405, 500, 605, 720, 885, 980, 1125, 1280, 1145, 1680, 2000, 2180, 2405, 2605, 2720, 2845 mH, were used AMINA to obtain the stable value of  $V_n$  as well as the least value of the  $I_{fault}$ .
- Parallel resonance was used to limit the PC L. (vi)
- The selected threshold value of  $I_{adap}$  is <20% of the  $I_{Rated}$ . (vii)
- The considered threshold value of the  $I_{fault}$  for the overcurrent protective relay (viii) is 20%.
- (ix) The considered total relay operation time is 0.3 Sec.
- (x) The simulation tools of Matlab 2010a were used to attain the results.
- Parallel resonance of L and C was selected to obtain the optimal APC. (xi)
- (xii) The optimizing heuristic techniques of AFLC, AANFIS, and AABCNN were used.
- (xiii) For the validity of offline AABCNN results, an online Texas Instrument chip (eZdsp F28335) in Matlab was chosen.

### 1.5 **Research Contributions**

This research made many contributions to the main knowledge by achieving the proposed research objectives. The primary purpose of the power protection system in a power system (PS) network is to trap the fault or abnormal situation quickly and take action instantly to remove it while saving the PS network against damage. But, there are certain limitations for the protection system to work efficiently. Due to certain limitations, the difficulty in extracting information from existing devices indicates that either the equipment is malfunctioning or out of reach, i.e., below/above the limits. One of the problems in PC-protected MVDN facing SLGF is the time of detection of fault and the time of arc extinguishing when the threshold value is below 20%. Therefore, in this research, the SLGF in a real MVDN of 11 kV, 4-busbar at Babylon, Meddle Euphrates power station of Iraq, was selected for the simulation in MATLAB. A total of three algorithms, i.e., FLC, ANFIS heuristic adaptive, and one novel ABCNN novel adaptive, were developed. The results were obtained for the time of detection of SLGF and the time of extinguishing the electric arc. For the validity, the FLC and ANFIS were confirmed by comparing with other research and novel ABCNN by testing on an online system using Texas Instrument Chip (eZdsp F28335) in MATLAB. The research contributions of this research are summarised below.

Initially, the compensation of  $I_L = I_C$  in the parallel resonance, while the optimized value of *L* of the PC was obtained experimentally in the PS laboratory of the Babylon University of Iraq. It was found to be L = 1145 mH. It helped to reduce the  $I_{fault}$  as well as to obtain the minimum  $V_n$ .

Secondly, the time of detection of SLGF in MVDN from 0.0075 Sec has been reduced to 0.005, 0.004, and 0.002 Sec while applying AFLC, AANFIS, and AABCNN, respectively.

Thirdly, the time of extinguishing of the electric arc in the case of SLGF in MVDN from 0.0675 Sec has been reduced to 0.065, 0.051, and 0.045 Sec while applying AFLC, AANFIS, and AABCNN, respectively.

Finally, the validation of the offline novel AABCNN was compared with the practical/online AABCNN using a Texas Instrument chip (eZdsp F28335) in MATLAB. It was found to be almost.

### 1.6 Organization of Thesis

This thesis is divided into five chapters. The following is a synopsis of each chapter: Chapter one is an introductory chapter that includes the background of the problem of SLGF in MVDN, its consequences, and remedial actions. Furthermore, this chapter



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### LIST OF PUBLICATIONS

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