ARTIFICIAL IMMUNE SYSTEM BASED ON REAL VALUED NEGATIVE SELECTION ALGORITHMS FOR ANOMALY DETECTION

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A dissertation submitted in Partial fulfillment of the requirement for the award of the Degree of Master of Computer Science (Soft Computing)

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FEBRUARY 2015

ABSTRACT

The Real-Valued Negative Selection Algorithms, which are the focal point of this research, generate their detector sets based on the points of self data. Self data are regarded as the normal behavioral pattern of the monitored system. In this research, the Real-Valued Negative Selection with fixed-sized detectors (RNSA) and Real-Valued Negative Selection with variable-sized detectors (V-Detector) were applied for classification and detection of anomalies. The issue of integrity and confidentiality of data have been in existence for decades. Data have been tampered and altered either by a computer user or unauthorized access via hacking. In this research, the Negative Selection Algorithms were deployed. On the contrary, the experiments with various and well-known datasets show that NSAs have great flexibility to balance between efficiency and robustness and to accommodate domain-oriented elements in the method. Classifier algorithms, namely the Support Vector Machine and K-Nearest Neighbours were used for benchmarking the performance of the Real-Valued Negative Selection Algorithms. Experimental results illustrate that RNSA and V-Detector algorithms are suitable for the detection of anomalies, with SVM and KNN producing significant efficiency rates and increase in execution time. The results shown in this study illustrate the effectiveness of the anomaly detection techniques on Iris, Balance-Scale, Lenses and Hayes-Roth datasets. On the whole, the RNSA and V-Detector outperformed SVM and KNN on all datasets by producing higher detection rates, lower false alarm rates and execution times. This shows that the Negative Selection Algorithms are equipped with the capabilities of detecting changes in data, thus appropriate for anomaly detection. With respect to all the algorithms, V-Detector proved to be superior and surpassed all other algorithms based on performance and execution time.



ABSTRAK

Algoritma Pemilihan Nilai Nyata Negatif yang menjadi tumpuan penyelidikan ini menghasilkan set pengesannya berdasarkan kepada titik data sendiri. Data sendiri dianggap sebagai corak tingkah laku normal bagi sistem yang dipantau. Dalam penyelidikan ini, Pemilihan Nilai Nyata Negatif dengan pengesan bersaiz tetap (RNSA) dan Pemilihan Nilai Nyata Negatif dengan pengesan bersaiz boleh ubah (Pengesan-V) digunakan untuk pengelasan dan pengesanan anomali. Isu integriti dan kerahsiaan data telah wujud selama beberapa dekad. Data telah terusik dan diubah sama ada oleh pengguna komputer, atau capaian yang tidak dibenarkan melalui penggodaman. Dan dalam penyelidikan ini, algoritma pemilihan negatif telah digunakan. Sebaliknya, eksperimen dengan data yang pelbagai dan terkenal menunjukkan bahawa NSA mempunyai daya fleksibiliti untuk mengimbangi antara kecekapan dan keteguhan dan untuk menampung unsur berorientasikan domain dalam kaedahnya. Algoritma pengelasan, iaitu Mesin Vektor Sokongan dan K-Jiran Terdekat digunakan untuk penandaarasan prestasi algoritma pemilihan nilai nyata negatif. Hasil uji kaji menunjukkan bahawa algoritma RNSA dan Pengesan-V sesuai untuk pengesanan anomali, dengan SVM dan KNN yang menghasilkan kadar kecekapan ketara dan peningkatan dalam masa pelaksanaan. Keputusan yang ditunjukkan dalam kajian ini menggambarkan keberkesanan teknik pengesanan anomali pada set data Iris, Balance-Scale, Lenses dan Hayes-Roth. Pada keseluruhannya, RNSA dan Pengesan-V mengatasi SVM dan KNN pada semua set data dengan menghasilkan kadar pengesanan yang lebih tinggi, kadar isyarat palsu dan waktu pelaksanaan lebih rendah. Ini menunjukkan bahawa algoritma pemilihan negatif dilengkapi dengan keupayaan mengesan perubahan dalam data, dengan itu sesuai untuk pengesanan anomali. Berkenaan dengan semua algoritma, Pengesan-V terbukti unggul dan melepasi semua algoritma lain berdasarkan prestasi dan masa pelaksanaan.



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LIST OF SYMBOLS AND ABBREVIATIONS

AIS - Artificial Immune Systems

ALC - Artificial lymphocytes

RNSA - real-valued negative selection algorithm with fixed

detector

V - Detector - real-valued negative selection with variable detector

HIS - Human Immune System

SVM - Support Vector Machine

KNN - K-Nearest Neighbours

NIS - Natural Immune System

NSA - Negative Selection Algorithm

S - Self

 R_0 - set of competent detectors

L - length strings

R - set of competent detectors

RNS - Real-Valued Negative Selection

r - radius of detection

 η - adaptation rate

t - once a detector reaches this age it will be considered

to be mature

τ - decay rate

d - Detector

 r_s - self radius

*c*₀ - estimated coverage

 D_{max} - maximum number of detectors

 r_d - variable radius

 M_{max} - limit of the counter

H - Hyperplanes



F(x)Margin

Output y

training or test pattern х

weight vector w

bBias

vector components $w_i x_i$.

UCI Machine Learning Repository

KEEL Knowledge Extraction based on Evolutionary

Learning

initial value of vector x_i

 Z_i normalized data

SOM Sequential Minimal Optimization

Ccomplexity factor

WEKA NKU TUN AMINAI Waikato Environment for Knowledge

k Number folder MI option

NNge Non--Nested generalized exemplars

DR **Detection Rate**

FAR False Alarm Rate

 \boldsymbol{A} Actual normal class

TP True Positives

FN False Negatives

FP False Positives

TN True Negatives

ABActual anomalies class

CPU Central Processing

MATLAB Matrix Laboratory

IEEE Institute of Electrical and Electronics Engineering

CHAPTER 1

INTRODUCTION

1.1 Overview

A record is said to be anomalous or outlying if its behavior does not conform to the behavior of the majority of the dataset. There has been an increasing interest because its presence could indicate unauthorized usage of the system, a failure in part of the system or a diagnosis of a disease. Many domains require anomaly detection systems. One of them is anomaly detection, in which a user can try to gain extra privileges of the system or an unauthorized user can try to gain access to the system (Amer, 2011).

Additionally, anomaly detection is essentially a rare event problem that has been called and used interchangeably with various terms such as deviation detection, outlier analysis, fraud detection, exception mining, mining rare classes, and others. Similarly, a very minute fraction of the total transaction constitutes the anomalilent activities executed (Tuo *et al.*, 2004).

Thus, anomaly detection can be applied in many applications, where there are different costs for false positives and false negatives that are similar to different datasets for anomaly detection. There are biased and unsatisfactory results, especially with different costs of false positives and false negatives. Under these conditions, it is important to train the classification model under a cost sensitive procedure and also to evaluate the classifier performance more accurately (Gadi *et al.*, 2008).

Over the last few years, more intelligent decision making techniques have been inspired by nature, e.g. evolutionary algorithms, ant colony optimization and simulated annealing. More recently, a novel computational intelligence technique inspired by immunology has emerged and called Artificial Immune Systems (AIS). The immune system is complex and powerful. It is characterized by special features



such as noise tolerance, robustness, diversity, reinforcement learning memory, dynamic, distributed, multilayered and adaptive. These features give the immune system a great advantage in detecting lots of different types of pathogens, both known and unknown, and also destroying pathogens. The techniques inspired by the immune system have already been useful in solving some computational problems (Dasgupta *et al.*, 2011).

AIS can be seen as a pattern recognition system and consists of artificial lymphocytes (ALC) that can classify any pattern either as part of a predetermined set of patterns or otherwise, and in training, only positive examples are required. As such, AIS lends itself to application of fraud detection problems (Graaff *et al.*, 2011). The definition of AIS by Sridevi *et al.* (2012) as adaptive systems is inspired by theoretical immunology and observed immune functions, principles and models, which are applied for problem solving, which certifies its suitability for application in this study.

AIS with two types of Negative Selection Algorithms using real-valued coordinates, namely Real-Valued Negative Selection Algorithm (RNSA) with fixed detector and Real-Valued Negative Selection with variable detector (V-Detector) are the focus of this study. The immune system metaphors relevant to AIS are described in detail in Chapter 2. Furthermore, there is a comparison with other classification algorithms such as Support Vector Machine (SVM) and K-Nearest Neighbors (KNN). The real-valued Negative Selection Algorithms and the benchmarked algorithms are tested and applied to various dataset, with the step by step algorithm walk-through is revealed.

1.2 Problem Statement

In a modern day life, anomaly is one of the major causes of great losses (Graaff *et al.*, 2011). Anomalies are patterns in data that do not conform to a well-defined notion of normal behavior. They may be induced in the data for various reasons, such as malicious activity, for example, credit card fraud, cyber-intrusion, terrorist activity or breakdown of a system, but all of the reasons have the common characteristics that make them interesting to the analysts. Many types of anomaly exist in different application fields, namely point anomalies, contextual anomalies, and collective anomalies. Different anomaly detection techniques have been developed and

proposed in handling issues related with keeping the integrity of data, and have been applied to fault tolerance, robotic control, network intrusion detection, and bioinformatics.

In general, the problem of anomaly detection can be seen as a two or more class classification problem. Given an element from a given problem space, the system should classify it as normal or abnormal. However, this is a very general characterization since it can correspond to very different problems depending on the specific context where it is interpreted. Therefore, from a statistical point of view, the problem can be seen as that of outlier detection, which is referred to as an observation deviating from other observations and triggering uncertainty as to how it was generated (Gonzalez & Dasgupta, 2003).

Since the 19th century, various attempts have been made to resolve the problems of anomalies. Many modern techniques exist in literature that are based on Artificial Intelligence, Neural Network, Bayesian Network, Fuzzy logic, K-Nearest Neighbor Algorithm, Support Vector Machine, Decision Tree, Fuzzy Logic Based System, Machine learning, Sequence Alignment, Genetic Programming and others, which have evolved in detecting various anomaly (Tripathi *et al.*, 2013).

The Negative Selection Algorithm is equipped with properties that make it suitable for use in detecting anomalies. The properties are as follows: (1) No prior knowledge of intrusions is necessary, (2) Detection is probabilistic but tunable, meaning a complete repertoire of detectors will not be generated (i.e. a set of detectors that covers all possible non-self strings). Instead, it is contented with matching all but a small fraction of non-self strings in exchange for a smaller set of detectors, (3) The detection scheme is inherently distributable, (4) The set of detectors at each site can be unique. This means that if one site is compromised, others would still be protected, and (5) The set of self strings and the detector set are mutually protective, meaning that the detector set protects the self set against change and vice versa (D'haeseleer *et al.*, 1997).

The field of Artificial Immune Systems which began in the early 1990s serves as alternative and efficient algorithms for detecting anomalies to the already existing methods. The immune system shows computational strength from different aspects of problem solving. In defining Artificial Immune System, there seems to be no fundamental definition, and many others are focusing on anomaly detection (Garrett, 2005).

They were inspired by the Human Immune System (HIS) which is robust, decentralized, error tolerant, and adaptive in nature. Also, the Artificial Immune System appears to be precisely tuned to the problem of detecting and eliminating infections (Tuo et al., 2004). There are a number of AIS models used in pattern recognition, fault detection, computer security, and a variety of other applications in the field of science and engineering. Most existing AIS algorithms imitate one of the following mechanisms of the immune system: negative selection, dendritic cell, immune network, or clonal selection. These models emphasize on designing and applying computational algorithms and techniques using simplified models of various immunological processes and functionalities (Aziz et al., 2012). Negative Selection-based Algorithm (Dasgupta et al., 2011) has potential applications in various areas, in particular anomaly detection.

Considering all the above advantages of AIS, this work attempts to classify different datasets by using AIS with Negative Selection Algorithms, namely the RNSA and V-JNKU TUN AMINA Detector, which are data-driven models to alleviate the difficulty in anomaly detection in various datasets.

Aim of the Study 1.3

The aim of this study is to apply AIS with Real-Valued Negative Selection Algorithms for anomaly detection problem through classification of four datasets.

Objectives of the Study

In order to achieve the above mentioned research aim, several objectives have been set, which are listed below:

- i. To apply a detector model based on Artificial Immune System (AIS) with Negative Selection Algorithms; the RNSA and V-Detector.
- ii. To classify the datasets using the algorithmic models in (i).
- iii. To compare and evaluate the performance of the AIS algorithms with other classifiers, namely the SVM and KNN based on Detection Rate, False Alarm Rate, and CPU Time.



1.5 **Scope of the Study**

This research focuses on the use of two kinds of Real-Valued Negative Selection Algorithms, namely the RNSA and V-Detector. For benchmarked purpose, two popularly known classification algorithms; Support Vector Machine and K-Nearest Neighbors have been adopted in this study. Three datasets were retrieved from the UCI Machine Learning Repository, which are the Iris data consisting of three classes of Iris Setosa, Iris Versicolour and Iris Virginica instances; and the Balance-Scale data constituting three classes of Left, Balance and Right; and the Lenses constituting three classes, which are the patient that should be fitted with hard contact, soft contact, and no contact lenses. Also, one dataset was retrieved from KEEL Knowledge Extraction based on Evolutionary Learning, which is Hayes-Roth consisting of three classes (1, 2, 3). As a measure of performance for comparison between the RNSA algorithms and benchmarked algorithms, three (3) evaluation TUN AMINAH metrics were considered, namely Detection Rate, False Alarm Rate, and time.

1.6 Significance of the Study

The importance of this research is to ascertain the accuracy rates of the Real-Valued Negative Selection Algorithms of RNSA and V-Detector when tested and applied on different datasets. The benchmark with other classification algorithms will give an insight on their performances for anomaly detection analysis. Therefore, it becomes essential to maintain the viability of the system using Negative Selection Algorithms, which significantly reduces false alarms.

1.7 **Thesis Organization**

The remaining part of this thesis is organized into the following chapters. Chapter 2 concerns with the relevant background information regarding using Real-Valued Negative Selection Algorithms for classification and detection purposes in the following order: (1) overview of RNSA and V-Detector architectures, (2) the advantages of RNSA and V-Detector, and (3) several techniques and applications that have been employed in the classification of four datasets. This chapter also



highlights the virtues and limitations of the existing algorithms, and arguments are brought forward for alternative methods that can be used for classifying datasets.

In Chapter 3, brief description on the steps of applying the RNSA algorithms of RNSA and V-Detector and benchmarked algorithms of SVM and KNN to datasets, rationale of selecting parameters for each algorithm, as well as evaluation method on the algorithms based on Detection Rate, False Alarm Rate, and CPU time are presented.

Comprehensive experimental evaluations of the algorithms used are presented in Chapter 4. The classification results of each algorithm with graphical representation constitute the fourth chapter. Lastly, Chapter 5 summarizes the work done, contributions, and several recommendations are suggested in order to improve the performance of the algorithms used.

1.8 Chapter Summary

The need for ensuring integrity and confidentiality in data has prompted computer scientists and researchers in proffering ways and avenues to adequately secure information. This stems from anomalies or abnormality, and therefore detection improvement requires continuous efforts in many fields, including Artificial Immune System (AIS). For several data, AIS classifiers have proven their ability in successfully classifying those data by revealing the abnormalities therein. As such, this research concentrates on using Real-Valued Negative Selection Algorithms with the focus on fixed detector (RNSA) and variable detector (V-Detector) in classifying different datasets.

CHAPTER 2

LITERATURE REVIEW

2.1 Introduction

This chapter introduces and discusses the idea behind anomaly detection, its definition and also different techniques in alleviating its harm. One of those techniques is Artificial Immune System (AIS) algorithms. Focus is directed at AIS algorithms that are based on the Biological Immune System of two types of negative selection, namely Real-Valued Negative Selection Algorithm (RNSA) and Variable-Detector Negative Selection Algorithm (V-Detector). Details of their working processes are elaborated upon. Also, exploration of the classifier algorithms of SVM and KNN are discussed.

AIS algorithms are machine-learning algorithms that embody some of the principles and attempts to take advantages of the benefits of natural immune systems in tackling complex problem domains (Brownlee, 2005). AIS is a branch of biologically inspired computation focusing on many aspects of immune systems. AIS development can be seen as having two target domains; the provision of solutions to engineering problems through the adoption of immune system inspired concepts and the provision of models and simulations to study immune system theories (Read *et al.*, 2012).

The motivation for building immune inspired solutions to engineering problems arises from the identification of properties within the immune system that are attractive from an engineering perspective. These include the self-organization of a huge number of immune cells, the distributed operation of the immune system throughout the body, pattern recognition and anomaly detection to enable the immune system to recognize pathogens, and optimization and memory to improve and remember immune responses (Muda & Shamsuddin, 2005).

Anomaly detection provides an alternate approach than that of traditional intrusion detection systems and suggests modelling both normal and malicious behavior (Jung et al., 2004). It should be noted that not all anomalies are malicious in nature (Muda & Shamsuddin, 2005), and anomalies also have potentials to translate into significant critical and actionable information (Chandola et al., 2009). Some of the uses of anomaly detection are detecting precedent attack behavior, zero day attack detection, intrusion detection, insider threat detection, situational awareness, and the validation and assisting with signature data. The targeted aim is the thoughtful process is differentiating what is normal from abnormal.

2.2 Transition from Biological Immune System to Artificial Immune System

The concept and theory of the Artificial Immune System will be incomplete without mentioning its source of inspiration in bringing its algorithms to the Biological Immune System. The body has different mechanisms to protect itself (self cells) from harmful foreign materials. One of these mechanisms is the natural immune system, and its main purpose is to detect and destroy any unwanted foreign cells (non-self cells) that could be harmful to the body. These non-self cells are known as antigens, and the natural immune system produces antibodies (as explained below) to bind to these antigens.

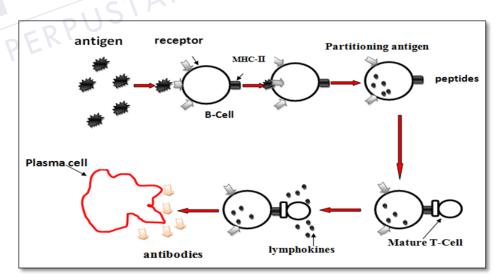


Figure 2.1:Partitioning an Antigen and Proliferation of a B-Cell into a Plasma Cell

Natural Immune System (NIS) mainly consists of lymphoid organs that create lymphocytes. The two most familiar lymphocytes are the T-Cell and B-Cell, in which both are formed in bone marrows as shown in Figure 2.1. Both T-Cell and B-Cell have receptors on their surfaces to bind with an antigen (Graaff *et al.*, 2011; Andrews, 2008). The immune system is a natural resistance to diseases using sophisticated adaptive mechanisms intended either to destroy the invaders or to neutralize their effects. As illustrated in Figure 2.2, the Biological Immune System can be classified according to functionality into four different layers of defence, which are physical, physiological, innate and adaptive. Depending on the invaders type and behavior, the immune system responds to very basic infections, and the skin serves as a physical barrier and a first line of defence. When pathogens elude the skin barrier, there are physiological barriers that provide a non-survival environment for pathogens (Elhaj *et al.*, 2013).

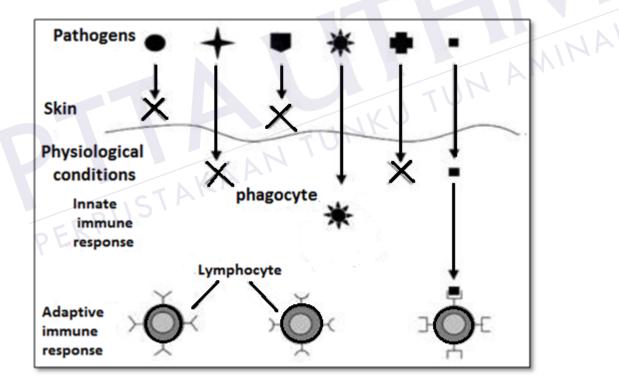


Figure 2.2: Multi-layer Structure of Immune System

The innate immune systems of these organisms are capable of self/non-self-discrimination, and also exhibit properties such as specificity, diversity and memory, which until recently have only been associated with adaptive immune systems. Low-level biological models of the mechanisms which give rise to these properties could provide important sources of inspiration for future AIS algorithms. However, if AISs

are to employ adaptive immune system mechanisms, then it is argued that they also need to incorporate innate immune system mechanisms, which control the adaptive immune system in biological organisms (Twycross & Aickelin, 2007).

Meanwhile, the artificial immune systems, techniques that are new to the scene of biologically inspired computation and artificial intelligence, are metaphor and abstraction from theoretical and based on empirical knowledge of the mammalian immune system. A robust biological process critical to the combating of disease in the body, the immune system is known to be distributed in terms of control, parallel in terms of operation, and adaptive in terms of function, all of which are features desirable for solving complex or intractable problems faced in the field of artificial intelligence (Brownlee, 2005).

There are a number of AIS models used in pattern recognition, fault detection, computer security, and a variety of other applications in the field of science and engineering (Aziz *et al.*, 2012). Most of these models emphasize on designing and applying computational algorithms and techniques using simplified models of various immunological processes and functionalities (De Castro & Timmis, 2002; Dasgupta, 2006). Also, AIS has gained increasing interest among researchers in the development of immunebased models and techniques to solve diverse complex computational or engineering problems (Al-Enezi, 2012).

Researchers have explored the main features of the AIS mechanisms and exploited them in many application areas. Based on their aspects, some AIS techniques have been found to be more suitable for certain application areas compared to other AIS approaches. It has been found that Negative Selection Models and Algorithms are widely used in fault detection and computer security applications utilizing the self/non-self-recognition aspect. Alternatively, the artificial immune network approaches have been used in clustering, classification, data analysis and data mining applications. The clonal selection models are used mostly for optimization problems (Al-Enezi al., 2009). The Danger Theory Project/Dendritic Cell Algorithm concludes the major AIS approaches that exist in literature, and they are targeted at anomaly detection and computer security applications based on the identification of danger rather than differentiating between self/non-self

Negative Selection Algorithm (Greensmith & Aickelin, highlighted by 2007). Based the above mentioned application areas on of the AIS approaches, and in line with the objective of detecting fraud for this study, Selection Algorithm Dendritic Cell Algorithm Negative and perfectly within the research confines.

Several definitions of AIS exist in literature but only three have gained popularity among AIS researchers.

- AIS is a new technique for solving combinatorial optimization problems. AIS are computational systems that explore, describe and apply different mechanisms inspired by Biological Immune Systems in order to solve problems in different domains (Guezouri & Houacine, 2012).
- AIS is a technique new to the scene of biologically inspired computation and artificial intelligence, based on metaphor and abstraction from theoretical and empirical knowledge of the mammalian immune system (Brownlee, 2005).
- The field of AIS is one of the recent biologically inspired approaches to emerge from computer science (Muda & Shamsuddin, 2005). UNKU TUN

2.3 **Anomaly Detection**

Anomaly detection refers to the problem of finding patterns in data that do not conform to expected behavior. In understanding the principle of anomaly detection, an insight into what anomaly is all about needs to be clearly defined. An anomaly, which is also used interchangeably depending on the application area as outliers, aberrations, exceptions, or peculiarities, is defined as patterns behaving differently to the normal behavioral flow. There exist three basic types of anomalies, namely point anomalies, collective anomalies, and contextual anomalies. The point anomalies represent deviation in single data instance. When a deviation occurs with a group of data instance, the anomaly is collective. Also, deviation happening within a context depicts the contextual anomalies. Thus, anomaly detection is the process of identifying or recognizing abnormal behavioral changes in data (Lasisi et al., 2014). Anomaly detection finds extensive use in a wide variety of applications such as fraud detection for credit cards, insurance, health care, intrusion detection for cyber security, fault detection in safety critical systems, and military surveillance for enemy activities. The importance of anomaly detection is due to the fact that

anomalies in data translate into significant, and often critical, actionable information in a wide variety of application domains. For example, an anomalous traffic pattern in a computer network could mean that a hacked computer is sending out sensitive data to an unauthorized destination (Kumar, 2005). An anomalous MRI image may indicate the presence of malignant tumours (Spence *et al.*, 2001). Anomalies in credit card transaction data could indicate credit card or identity theft (Aleskerov *et al.*, 1997), or anomalous readings from a spacecraft sensor could signify a fault in some components of the spacecraft (Fujimaki *et al.*, 2005). Detecting outliers or anomalies in data has been studied in the statistics community as early as the 19th century (Edgeworth, 1887). Over time, a variety of anomaly detection techniques has been developed in several research communities. Many of these techniques have been specifically developed for certain application domains, while others are more generic.

2.4 Anomaly Detection Technique

Many modern techniques based on Artificial Intelligence, Data Mining, Neural Network, Bayesian Network, Fuzzy logic, Artificial Immune System, K- Nearest Neighbour Algorithm, Support Vector Machine, Decision Tree, Fuzzy Logic Based System, Machine Learning, Sequence Alignment, Genetic Programming and others have evolved in detecting various anomaly (Tripathi & Pavaskar, 2012; Singh & Narayan, 2012).

The various aforementioned techniques are either specific to certain application domains or more generic (Singh & Upadhyaya, 2012). The choice of which technique to use depends greatly on criteria and functionalities of each individual technique for the targeted application domain. In the following section, the AIS models of Negative Selection Algorithm using real-valued elements, namely RNSA and V-Detector for anomaly detection, are discussed in detail with their various components. Also, the selected classification algorithms in SVM and KNN are elaborated upon as well.

2.4.1 Negative Selection Algorithm (NSA)

Negative Selection Algorithm provides a mechanism to protect the self cells of the host, and also destroy unknown antigens (non-self cells). Within the highly-impregnable barrier of thymus, thymocytes (immature T-cells) mature by a pseudorandom genetic rearrangement of its receptors. Next (still in the thymus), these mature T-cells are exposed to self-peptides, and those that react strongly with the peptides are eliminated through a process called apoptosis. The rest of the mature T-cells that do not react with the self-peptides are subsequently released outside the thymus and into the body to fight against non-self antigens. The result of such a mechanism is that while on the one hand the (released) matured T-cells kill the non-self antigens; they are, on the other hand, non-reactive to the self (body) cells. Thus, Negative Selection Algorithm (NSA) may be viewed as a mechanism to discriminate the self from non-self cells (Dasgupta & Nino, 2008). There exist two types of NSA based on the data representation, which are the string (or binary) Negative Selection Algorithm, and the Real-Valued Negative Selection Algorithm. Detailed descriptions of the NSA types are reflected in the next section.

2.4.1.1 String (or Binary)-based Negative Selection Algorithm

NSA is one of the first immune-inspired change detection algorithms that was proposed (Balachandran *et al.*,2007). The process of keeping a computer away from intrusion can be regarded as distinguishing self and non-self. In the illumination of this idea, the research group led by Stephanie Forrest in the New Mexico University proposed the immune negative selection algorithm (Forrest *et al.*, 1994). This first implementation initially used a binary representation for the elements in the self/non-self space.

The main idea of the algorithm is to generate a set of detectors which do not harm self and distinguish the non-self (unauthorized user, virus, and others) from self (authorized users, protected data files, and others). This algorithm consists of censoring and monitoring processes as depicted in Figure 2.3 and Figure 2.4 respectively. The censoring phase caters for the generation of mature detectors. Subsequently, the system being protected is monitored for changes by the detectors



generated in the censoring stage (Forrest *et al.*, 1994). The algorithm constructs a set of competent detectors in the following steps:

- Step 1: Define a set of self S. The data being protected is viewed as a string. The string is split into several L-length substrings. The set of self consists of several substrings.
- Step 2: Generate a set of random candidate detectors R_0 . They are also L -length strings and are generated in some probability analytical ways.
- Step 3: Generate a set of competent detectors R. Strings from R_0 that match self are eliminated. Strings that do not match any of the strings in S become members of the detector collection R. This step is called censoring.
- Step 4: Monitor the changes of self. This is achieved by continually choosing one detector in R and testing to see if it matches with strings in S. If the self string matches one of the detector strings, a change would happen in S. Those changes are caused probably by intrusion, virus or misuse. This step is called monitoring.

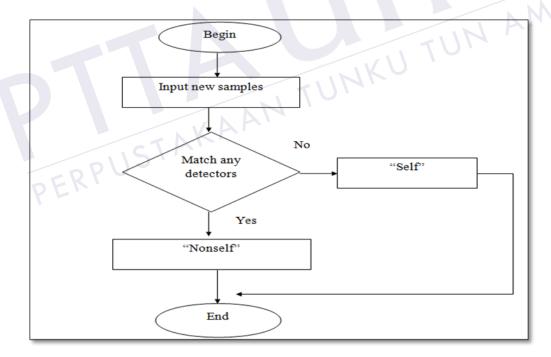


Figure 2.3: Censoring Stage

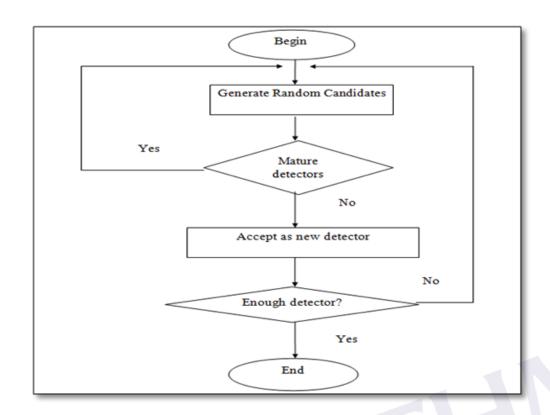


Figure 2.4: Monitoring Stage

2.4.1.2 Real-Valued Negative Selection Algorithm (RNSA)

The Negative Selection Algorithm proposition as shown in Figure 2.4 (Forrest *et al.*, 1994) suffers greatly from time complexity as it is exponential to the size of the matching window (the number of bits used to compare two binary strings). In order to tackle these problems, Gonzalez *et al.* (2002) proposed a Negative Selection Algorithm that uses real-valued representation of the self/non-self space. This algorithm, called Real-Valued Negative Selection (RNSA), tries to alleviate the scaling issues of binary negative selection algorithms while it uses various schemes to speed up the detector generation process. Different RNS algorithms used different geometric shapes such as hyper-rectangles, hyper-spheres and hyper-ellipses for covering the non-self space (Ji & Dasgupta, 2006).

The Real-Valued Negative Selection Algorithm using fixed sized detectors is based on a pre-specified number of detectors. This is not the best approach, and obviously provides no guarantee that the non-self space is completely covered. However, by selecting a large enough value for the number of detectors, the algorithm is expected to provide adequate results. Figure 2.5 provides pseudo-code for the generation phase of the algorithm.

Real-Valued Negative Selection (r, η ,t, τ , # of Detectors)

```
r: radius of detection
     n: adaptation rate
     t: once a detector reaches this, age it will be considered to
be mature
     τ: decay rate
Generate a random population of detectors based on # of Detectors
While stopping criteria is not satisfied
For each detector d_i,
         Calculate
                    the
                           shortest distance to any self point,
dist_min, and store the nearest
          point c_i
           While (dist\_min < r)
                  If age > t
                           Generate a new Detector d_i,
                  Else
                           Calculate direction (dir) using c_i,
                           Calculate \eta_i,
                           Move detector by: d_{(i+1)} = d_i + \eta_i *dir
                              Increase age + 1,
                              Recalculate dist_min and c_i
                  End If
           End While
            If (Not the first detector),
                     Calculate the shortest distance to all previous points,
detectors and self points,
                     dist min2, and store the nearest point c_i,
                     While (dist min2 < r)
                            If age > t
                                Generate a new Detector d_i,
                                Calculate direction (dir) using c_i,
                                Calculate \eta_i,
                                Move detector by: d_{(i+1)} = d_i + \eta_i *dir
                                     Increase age + 1,
                                     Recalculate dist_min2 and c_i
                             End If
                         End While
                            Store detector as d_i
             Else
                             Store detector,
  End
```

Figure 2.5: RNSA Pseudo-code

The input to the algorithm is a set of self samples represented by *n*-dimensional points (vectors). The algorithm tries to evolve a complement set of points called antibodies or detectors that cover the non-self space. This is accomplished by an iterative process that updates the position of the detector driven by two goals:

i. Move the detector away from the self points.

ii. Keep the detectors separated in order to maximize the covering of the non-self space.

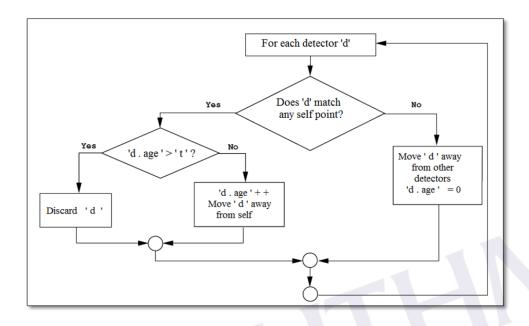


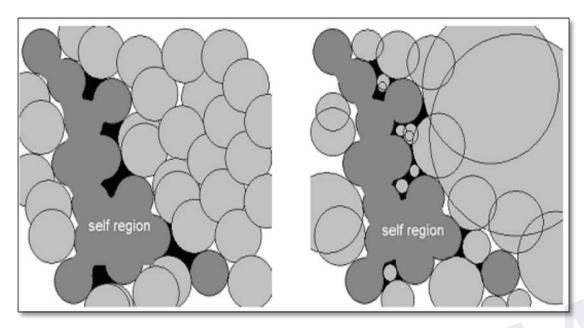
Figure 2.6: The Iterative Process of Real-Valued Negative Selection Algorithm

2.4.1.3 V-Detector Negative Selection Algorithm

The first implementation of the real-valued negative selection algorithm generated detectors, in which the distance threshold (or radius) was constant throughout the entire detector set. However, the detector features can reasonably be extended to overcome this limitation. Zhou and Dasgupta proposed a new scheme of detector generation and matching mechanisms for negative selection algorithms which introduced detectors with variable properties (Ji & Dasgupta, 2007).

The proposed algorithm includes a new variable parameter, which is the radius of each detector. The threshold used by the distance matching rule defines the radius of the detectors; it is an obvious choice to make variable considering that the non-self regions covered by detectors are likely to be variable in size. The flexibility provided by the variable radius is illustrated in Figure 2.6 (Ji & Dasgupta, 2006).





- a) Constant-sized Detectors
- b) Variable-sized Detectors

Figure 2.7: Comparison of Detector Coverage for Different Detector Schemes

Figure 2.7 illustrates several core advantages to the method of implementing variable-sized detectors. The first apparent advantage is that a larger area of non-self space is covered with fewer detectors. The issue of "holes" is a well-known problem with Real-Valued Negative Selection Algorithms. Tiny spaces between detectors and self points cannot be filled by constant-sized detectors as illustrated in black in Figure 2.7 (a). However, by using variable-sized detectors as shown in Figure 2.7 (b), smaller detectors can be generated to cover small holes while larger detectors cover the wider non-self space.

The control parameters of the V-Detector algorithm consist of the self radius r_s , the estimated coverage c_0 , and the maximum number of detectors D_{max} . The latter two are the central mechanisms for the stopping criteria; the maximum number of detectors is preset to allow the maximum allowable detectors in practice. The pseudo-code of the V-Detector is shown in Figure 2.8. The detection phase of the V-Detector algorithm is nearly similar as the fixed-sized detector algorithm. The only exception is the detector threshold utilized for the unknown data detection is based on the variable radius r_d assigned to each detector. If an unknown data instance is detected (i.e. the minimum distance to any detector is less than r_d), it is classified as non-self; otherwise it is classified as self (Dixon, 2010).

Real-Valued Negative Selection with Variable Detection Radius (r_s, M_{max}, D_{max})

```
Preset Control Parameters: r_s, M_{\max}, D_{\max}
While (m < M_{max}) / (i < D_{max})
      Generate a random Detector candidate di,
      Calculate the shortest distance to any self points, dist_min,
If (dist\_min < r_s)
        Return to top,
Else
        If (i = 1)
                  Store detector as di and dist_min = rdi,
                  Increment i + 1
Else
                  Calculate the shortest distance for each previous
detector, dist_min2,
                If (dist_min2 < rd)
                       m = m + 1,
                Else
                       Store detector as di and dist_min2 = rdi,
                       Increment i + 1
                       m = 0,
                  End If
             End If
        End If
End While
Figure 2.8: Real-Valued Negative Selection V-Detector Algorithm Pseudo-code
End
```

Support Vector Machine (SVM)

Support Vector Machine (SVM), an elegant tool for solving pattern recognition and regression problems, has been demonstrated to be valuable for several real-world applications. SVMs were introduced by Vladimir Vapnik and colleagues. The earliest mention was in 1979 by Vapnik, but the first main paper was published more than a decade later (Vapnik et al., 1995). Support Vectors Machine (SVM) is a powerful classification method based on the statistical learning theory (Shevade et al., 2000). SVM is also known as maximum margin classifier due to its ability to simultaneously minimize the empirical classification error and maximize the geometric margin instead of the traditional Empirical Risk Minimization principle used by other classifiers such as neural networks (de Pádua & Nascimento, 2012). SVM was originally designed for classification and regression tasks; however, it was later expanded in other directions. The essence of SVM method is construction of optimal hyperplane, which can separate data from opposite classes using the biggest possible margin. Margin is a distance between optimal hyperplane and a vector that lies closest to it. An example of such hyperplane is illustrated in Figure 2.9. As it can be seen in the drawing, there can be many hyperplanes that can separate two classes, but with regard to optimal choice.

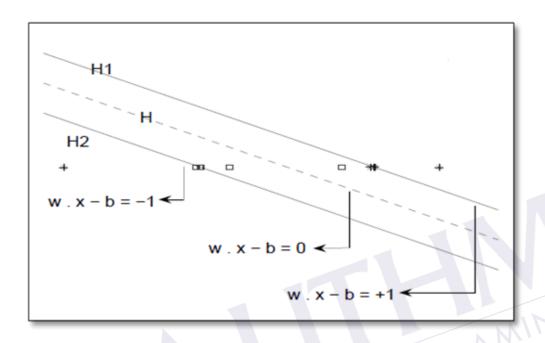


Figure 2.9: Linear Support Vector Machine

The margin F(x) and the hyperplanes as reflected in Figure 2.9 are depicted in Equations 2.2 through 2.5. H refers to hyperplanes, y refers to the output, x refers to a training or test pattern, w refers to the weight vector and the value b is the bias term. The term (w, x) refers to the dot product (liner) product, scalar product), which calculates the sum of the products of vector components $w_i x_i$.

1. Optimal hyperplane.

$$H: y = w. x-b = 0$$
 (2.1)

2. Supporting hyperplanes - parallel and equidistant to optimal hyperplane.

$$H_1: y = w \cdot x - b = +1$$
 (2.2)

$$H_2: y = w \cdot x - b = -1$$
 (2.3)

3. Margin - distance between optimal hyperplane and a vector that lies closest to it.

$$F(x) = w. x + b \tag{2.4}$$

where F(x) is a margin.

2.4.3 K-Nearest Neighbour (KNN)

K-Nearest Neighbour (KNN), originally proposed by Fix and Hodges, is a very simple instance-based learning algorithm (Fix & Hodges, 1951), and one of the most popular algorithms for text categorization. The idea behind K-Nearest Neighbour algorithm is quite straightforward. To classify a new dataset, the system finds the k nearest neighbours among the training dataset and uses the categories of the k nearest neighbours to weight the category candidates. One of the drawbacks of KNN algorithm is its efficiency, as it needs to compare a test dataset with all samples in the training set. In addition, the performance of this algorithm depends greatly on two factors, which are a suitable similarity function and an appropriate value for the parameter k (Li & Lu, 2003).

However, the k-nearest neighbour algorithm, which is most often used for classification, can also be used for estimation and prediction. The k-nearest neighbour is an example of instance-based learning, in which the training dataset is stored so that a classification for a new unclassified record may be found simply by comparing it to the most similar records in the training set (Marcoulides, 2005).

The traditional KNN classification has three limitations:

1. High calculation complexity: To find out the *k* nearest neighbour samples, all the similarities between the training samples must be calculated. When the number of training samples is less, the KNN classifier is no longer optimal, but if the training set contains a huge number of samples, the KNN classifier needs more time to calculate the similarities. This problem can be solved in 3 ways; reducing the dimensions of the feature space, using smaller datasets, or using an improved algorithm that can accelerate.

- 2. Dependency on the training set: The classifier is generated only with the training samples and it does not use any additional data. This makes the algorithm depend on the training set excessively; it needs recalculation even if there is a small change on the training set.
- 3. No weight difference between samples: All the training samples are treated equally; there is no difference between the samples with a small number of data and a huge number of data. Therefore, it does not match the actual phenomenon where the samples have uneven distribution commonly (Suguna & Thanushkodi, 2010).

2.5 Application of AIS in Anomaly Detection

Anomaly detection aims to detect anomalous observations from a system. There exist some sample observations from which the normal behavior is to be learned. This anomaly detection learning problem has many important applications including the detection of anomalous jet engine vibrations (Nairac *et al.*, 1997; Hayton *et al.*, 2001; King *et al.*, 2002), abnormalities in medical data (Tarassenko *et al.*, 1995; Campbell and Bennett, 2001), unexpected conditions in engineering (Desforges *et al.*, 1998) and network intrusions (Manikopoulos and Papavassiliou, 2002; Yeung and Chow, 2002; Fan *et al.*, 2001). For more information on these and other areas of applications, as well as many methods for solving the corresponding learning problems, a timeline of Artificial Immune System is tabulated in Tables 2.1 and 2.2.

Table 2.1: A timeline of AIS (1986 to 1999)

| Author (year) | Model or technique description | Type of representation used | Applications |
|-------------------------------|---|--|-----------------------------------|
| Farmer <i>et al</i> . (1986) | An immune system as a machine learning process. | Binary strings. | NIS modeling. |
| Bersini and Varela (1991) | A selective evolutionary strategy based on immune recruitment. | Real-valued vectors. | Optimization. |
| Forrest <i>et al.</i> (1993) | Exploration of pattern recognition in NIS using genetic algorithms. | Binary strings. | NIS modeling. |
| Forrest <i>et al</i> . (1994) | Original Negative Selection algorithm based on the T-cell recruitment process performed by the thymus. | Strings from finite alphabet. | Change and anomaly detection. |
| Kephart (1994) | A computer immune system architecture to detect and repeal virus. | Byte strings (signatures). | Computer security. |
| Ishiguro et al. (1995) | A decentralized behavior arbitration mechanism to control robots inspired by the NIS. | High-level representation (robot instructions). | Robot control. |
| D'Haeseleer et al. (1996) | An efficient implementation of the negative selection algorithm for binary strings. | Binary strings. | Change and anomaly detection. |
| Dasgupta and Forrest (1996) | A method to detect novelties in time series based on the negative selection algorithm. | Binary string representing Real values. | Anomaly and novelty detection. |
| Hajela <i>et al</i> . (1997) | The use of immune networks to improve the convergence of genetic algorithms applied to design optimization. | Binary strings. | Evolutionary design optimization. |
| Hunt et al. (1999) | A machine learning system (Jisys) based on immune networks. | Mixed numerical, categorical and string data. | Fraud detection. Learning. |

There has been an increase in AIS research since the middle of 1980s with a wide variety of works in different areas. Based on the survey of existing AIS literature, Tables 2.1 and 2.2 show a chronological list of some AIS models and techniques that are considered more relevant. The tables include a short description of each model or technique, along with the information about immunological mechanisms used, the type of representation, and the intended applications.

Optimization.

Clustering.

Dynamic learning.

Binary strings.

Real-valued

vectors.

Type of representation Model or technique description Author (year) Applications used A resource limited artificial immune Real-valued Data analysis. Timmis (2000) system (RAINE) for data analysisthat vectors. Clustering. extends the work of Cooke and Hunt De Castro and Real-valued An immune network learning Data analysis Von Zuben (2000) algorithm (aiNet). vectors. Clustering. An architecture for an artificial Computer Hofmeyr et al. immune system (Lisys) for computer Binary Strings. security. (2000)security. A machine fault tolerance mechanism Hardware fault Bradley and Binary strings. detection and based on immune system ideas Tyrrel (2000) (immunotronics). tolerance Initialization of A simulated annealing algorithm based De Castro and Real-valued feed-forward on immune systems (SAND) applied Von Zuben (2001) vectors. neural network to neural network initialization. weights. Real-valued vectors Tarakanov and An architecture to build chips that Pattern matching. (internally Dasgupta (2002) implement the immune system. represented as bits).

An approach to handle constraints in

GA based optimization.

A scalable AIS model for dynamic

unsupervised learning based on

immune network theory.

Coello and Cortez

(2002)

Nasraoui etal.

(2003)

Table 2.2: A timeline of AIS (2000 to 2003)

One of the first works that modelled Biological Immune System (BIS) concepts in developing pattern recognition was proposed by Farmer and colleagues. Their work proposed a computational model of the BIS based on the idiotypic network theory, which explains the immune memory mechanism. This work shows that the BIS can be viewed as a learning system and suggests that it can be used as an inspiration to build machine learning techniques (Farmer *et al.*, 1986). A later work by Hajela *et al.* (1997) used immune networks to improve the convergence of genetic algorithms for design optimization. Evolutionary computation shares many elements; concepts like population, genotype-phenotype mapping, and proliferation of the most fitted are present in different AIS methods. Some of the earlier work that combined BIS ideas with evolutionary computation was developed by Bersini and Varela

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