

POWER QUALITY IMPROVEMENT BY USING NON-LINEAR  
SLIDING MODE CONTROLLER WITH THE DYNAMIC VOLTAGE  
RESTORER

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I dedicate this thesis to my parents. Without their understanding, support and most of all love, the completion of this work would not have been possible. Finally dedicate this thesis to the spirit of my daughter granular Rokaya which did not prohibit this day



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## ABSTRACT

The essential issue of the power system network is power quality. The bus voltage must be maintained as a sinusoidal waveform. Many disturbances affect the supply voltage, such as notching, transients, voltage sag/swell. The major power quality problems are voltage sag/swell and harmonics, which cause tripping or malfunctioning the equipment. The linear PID controller's output suffers from a high amplitude of error when the input signals are noisy. This thesis gives an effective solution to protect the sensitive loads from disturbances by utilizing the dynamic voltage restorer. It is defined as a controlled voltage source connected in series between the sensitive loads and the network through a series transformer to inject a proper voltage magnitude to keep the sensitive loads at a constant value. The two non-linear controllers employ a robust differentiator known as an approximate sliding mode differentiator (ACSMD) with a non-linear sliding variable named a terminal PID sliding variable (TPIDSV) or arctan PID sliding variable (ARTPIDSV). Simulation results were carried out by MATLAB/Simulink to investigate the performance of the proposed controllers. The performance improvement obtained from the proposed techniques upon comparison with the case study as a linear PID controller, the steady-state error 85%-99%, the total harmonic distortion 2%-51%, the voltage sag indices 85%-99% and the load voltage magnitude 0.2%-8.7% for voltage sag and 0.08%-2.9% for voltage swell in all cases. The results illustrated the DVR structure's ability to overcome the system's disturbances, maintaining the voltage magnitude of the sensitive loads at a constant value, minimizing the steady-state of error, and keeping the THD at an IEEE standard. The DVR system performance is evaluated by utilizing three types of voltage sag indices.

## ABSTRAK

Isu penting rangkaian sistem kuasa adalah kualiti kuasa. Voltan bas mesti dikekalkan dalam bentuk gelombang sinusoidal. Pelbagai gangguan mempengaruhi voltan bekalan, seperti takik, transien, voltan lendut/kembang. Masalah kualiti kuasa utama ialah voltan lendut/kembang dan harmonik, yang menyebabkan peralatan tersekat atau tidak berfungsi. Output pengawal PID linier mengalami ralat amplitud tinggi ketika isyarat input berisik. Tesis ini memberikan penyelesaian yang berkesan untuk melindungi beban sensitif dari gangguan dengan menggunakan pemulih voltan dinamik. Ia didefinisikan sebagai sumber voltan terkawal yang dihubungkan secara bersiri antara beban sensitif dan rangkaian melalui transformer bersiri untuk menyuntikkan voltan yang betul untuk meletakkan beban sensitif pada nilai yang tetap. Kedua-dua pengawal tak linier menggunakan pembezaan kuat yang dikenali sebagai pembeza mod gelongsor anggaran (ACSMD) dengan pemboleh ubah gelongsor tak linier yang dinamakan pemboleh ubah gelongsor PID terminal (TPIDSV) atau pemboleh ubah gelongsor arctan PID (ARTPIDSV). Hasil simulasi dilakukan oleh MATLAB / Simulink untuk menyiasat prestasi pengawal yang dicadangkan. Peningkatan prestasi yang diperoleh dari teknik yang dicadangkan setelah dibandingkan dengan kajian kes sebagai pengawal PID linear, ralat keadaan stabil adalah 85% -99%, keseluruhan penyelewengan harmonik adalah 2% -51%, indeks voltan lendut adalah 85% -99% dan magnitud voltan beban 0.2% -8.7% untuk voltan lendut dan 0.08% -2.9% untuk voltan kembang dalam kesemua kes. Hasilnya menggambarkan kemampuan struktur DVR untuk mengatasi gangguan sistem, mengekalkan magnitud voltan beban sensitif pada nilai yang tetap, meminimumkan keadaan ralat stabil, dan menjaga THD pada tahap piawai IEEE. Prestasi sistem DVR dinilai dengan menggunakan tiga jenis indeks lendut voltan.

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## LIST OF SYMBOLS AND ABBREVIATIONS

$v_{L.dq}^{ref}$	- The reference load voltage
$v_{D.dq}^{ref}$	- The reference injected voltage
$v_{G.dq}$	- The symmetrical components of the measured phase voltages in dq
$v_{D.\alpha\beta}^{ref}$	- Reference injected voltage in $\alpha\beta$
$ v_{G.m.1} $	- The positive sequence component magnitude
$\varphi_1$	- The positive sequence component angle
$v_{G.0}$	- The zero component sequence
$V_{L.m}^{ref}$	- The desired load voltage
$v_{G.a.2}, v_{G.b.2}$ and $v_{G.c.2}$	- The negative sequence component of the instantaneous values of the three-phase
$v_{G.a.1}, v_{G.b.1}, v_{G.c.1}$	- The difference transformed into instantaneous values
$V_{inj-reference}$	- The reference injected voltage by DVR
$V_{D.a}^{ref}, V_{D.b}^{ref}, V_{D.c}^{ref}$	- The reference compensating signals injected by the DVR
$V_{D.a}^{ref}, V_{D.b}^{ref}$ and $V_{D.c}^{ref}$	- Reference injected voltage in three phase
$\dot{V}_{inj}$	- The second time derivative $V_{inj}$
$ error_{dq0} $	- The absolute error signal in dq0
$[sign(\sigma)]_{eq}$	- The equivalent operator
$\dot{S}(e)$	- The derivative sliding variable
$THD_a, THD_b$ and $THD_c$	- The THD for phase a,b and c
$I_L$	- Filter inductor current

$I_g$	- The source current
$R_f, L_f, C_f$	- The resistance, inductance and the capacitance of the filter
$V_{G,a}, V_{G,b}$ , and $V_{G,c}$	- The AC three phase system
$V_{G,d}, V_{G,q}$	- The two-phase system by utilizing $\alpha\beta$ /dq
$V_{G,\alpha}, V_{G,\beta}$	- The two-phase system by utilizing abc/ $\alpha\beta$
$V_{L,d}, V_{L,q}$ and $V_{L,0}$	- The load voltage in dq0
$V_d$ and $V_q$	- The DC component of dq transform method
$V_{inj}$	- The DVR injected voltage
$V_{nom}$	- Nominal voltage
$V_{ref,d}, V_{ref,q}$ and $V_{ref,0}$	- The reference voltage in dq0
$e_a(t)$ and $\dot{e}_a$	- The actual error signal and error derivative
$\mu F$	- Micro farad
AC	- Alternating current
ACSM	- Approximate classical sliding mode differentiator
ANF	- Adaptive notch filter
ARTPIDSV	- Arctan PID sliding variable
CBEME	- Computer and Business Equipment Manufacturers Association
CPD	- Custom Power Device
CSA	- Cuckoo search algorithm
DC	- Direct current
$de/dt$	- The deravative of error
DFIG	- Doubly feed induction generator
DG	- Distributed generation
dq0	- The synchronous reference frame
DSC	- Delayed Signal Cancellation
DSTATCOM	- Distribution Static Synchronous Compensator
DVR	- Dynamic Voltage Restorer
$e$	- The error signal
EKF	- Extended KF
EPRI	- Electric Power Research Institute
$E_{VS}$	- Voltage sag energy

$f$	- The frequency
<i>FACTS</i>	- Flexible AC transmission system
<i>FBA</i>	- Flower pollination algorithm
<i>FFT</i>	- Fast Fourier transform
<i>FT</i>	- Fourier Transform
<i>GOA</i>	- grasshopper optimization algorithm
<i>GTO</i>	- Gate Turn-Off
<i>GWO</i>	- Grey wolf optimizer
<i>HFL-DVR</i>	- High-frequency-link-DVR
<i>Hz</i>	- Hertz
<i>IC</i>	- Incremental conductance algorithm
<i>IDVR</i>	- Interline DVR
<i>IEC</i>	- International electrotechnical commission
<i>IEEE</i>	- Institute of electrical and electronics engineers
<i>IGBTs</i>	- Insulated Gate Bipolar Transistors
<i>IGCT</i>	- Integrated Gate Commutated Thyristor
<i>IOFL</i>	- Input-Output feedback Linearization
<i>ITAE</i>	- Integral time absolute error
<i>ITIC</i>	- Information Technology Industry Council
<i>KF</i>	- Kalman filtering
$K_p, K_i$ and $K_d$	- The Proportional, integral and Derivative gains
<i>KVA</i>	- Kilo volt-ampere
<i>kVAr</i>	- Kilo volte ampere reactive
<i>KW</i>	- Kilo watt
<i>LES</i>	- Least error squares
<i>LPF</i>	- Low pass filter
<i>MLIs</i>	Multi-level inverters
<i>MOSFETs</i>	- Metal Oxide Semiconductor Field Effect Transistors
<i>MPPT</i>	- Maximum power point tracking
<i>MVA</i>	- Mega volt-ampere
<i>ns</i>	- Nano second
$\theta$	- The angle used in transformation

<i>PBC</i>	- Passivity-based control
<i>PCC</i>	- Point of common coupling
<i>PF</i>	- Power factor
<i>PI</i>	- Proportional-Integral
<i>PID</i>	- Proportional integral derivative
<i>PIDSV</i>	- PID sliding variable
<i>PLL</i>	- Phase-locked loop
<i>PQ</i>	- Power quality
<i>PR</i>	- Proportional-resonant
<i>PSD</i>	- Power spectral density
<i>PSO</i>	- Particle swarm optimization
<i>PU</i>	- Per unit
<i>PV</i>	- The photovoltaic system
<i>PVUR</i>	- Phase voltage unbalance rate
<i>PWM</i>	- Pulse width modulation
<i>R</i>	- The resistance
<i>RMS</i>	- Root mean square
<i>rpm</i>	- Root per minute
<i>S(e)</i>	- The sliding variable
<i>SA</i>	- Surge Arrester
<i>SHE</i>	- Selective harmonic elimination
<i>SMC</i>	- Sliding mode controller
<i>SMES</i>	- Super-conducting Magnetic Energy Storage
<i>SPWM</i>	- The sinusoidal pulse-width modulation
<i>SRFT</i>	- Synchronous reference frame theory
<i>SS</i>	- Detroit Edison sag score
<i>SSTS</i>	- Solid-State Transfer switch
<i>STF</i>	- Self-tuning filter
<i>STFT</i>	- Short-time Fourier transform
<i>SVC</i>	- Static Var Compensator
<i>SVPWM</i>	- The space vector PWM
<i>T</i>	- The time during the sag in a milliseconds
<i>t</i>	- Time in second

$T1$	- Transformer no.1
$T2$	- Transformer no.2
$T3$	- Transformer no.3
$THD$	- Total harmonic distortion
$THD_v$	- The total harmonic distortion of voltage
$TPIDSV$	- Terminal PIDSV
$u(t)$	- The input of the differentiator
$UPS$	- Uninterruptible Power Supply
$USA$	- United states of america
$UVE$	- Unit vector estimator
$V$	- Volt
$V_-$	- The negative voltage sequence
$V(t)$	- Voltage magnitude at time t
$V_+$	- The positive voltage sequence
$V_A, V_B, \text{ and } V_C$	- Voltages at phase A,B and C
$V_A, V_B, \text{ and } V_C$	- The RMS phase voltages
$V_{avg}$	- The average phase voltage
$VD$	- Voltage Disturbances
$V_{DC}$	- The voltage of the DC storage
$V_{dev}$	- The deviation from the average phase voltage
$V_{DVR}$	- Voltage injection of the DVR
$VSC$	- Voltage Source Converter
$VSI$	- Voltage source inverter
$VSLEI$	- Voltage sag lost energy index
$W$	- The lost energy
$WFFT$	- Windowed Fast Fourier Transform
$WT$	- Wavelet Transform
$\sigma$	- The observer sliding variable
$\Omega$	- Ohm
$k \text{ and } C$	- The gain be selected to ensure $\sigma$ go to zero
$v$	- The LPF output
$x$	- Variable introduce in differentiator design
$y(t)$	- The output of the differentiator

- $\gamma(t)$  - The source of the steady state of error
- $\delta(t)$  - The switching function
- $\delta(t)V_{dc}$  - The control input
- $\delta e(t)$  and  $\delta \dot{e}$  - The uncertainty (noise) in the error signal and the error derivative
- $\lambda, q$  and  $p$  - The gain be selected to ensure S go to zero
- $\tau$  - The time constant



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**PTTA UTHM**  
PERPUSTAKAAN TUNKU TUN AMINAH



# CHAPTER 1

## INTRODUCTION

### 1.1 Introduction

In recent years, power quality has received significant interest in the industrial distribution system. The disturbances like voltage sag/ swell, flicker, and harmonics are the common power quality problems [1]. In the meantime, power quality problems can be defined as a deviation of voltage, current, and frequency from its standard values in the power system [2,3]. The increased use of non-linear electronic control devices in electrical power systems could increase power quality deterioration. This means that more focus is needed by power industry agents [4]. However, from the perspective of industrial and commercial producers, a low power quality suffering in terms of money, time, and resources [2].

In terms of power quality, voltage sag and swell are core problems in the power systems at the distribution and transmission sides. Voltage sag or voltage dip can be described as the short duration of voltage drop in RMS (root mean square) from its standard voltage value, which is lower than the nominal voltage range of 0.1 to 0.9 per unit (PU) between half-cycle to 1 minute. Depending on the fault types, the voltage sags can either be balanced or unbalanced. However, they always have unpredictable scales. Voltage swell is characterized as the fast increment in RMS (root mean square) voltage value from the standard voltage over the ostensible esteem, extending from 1.1 to 1.8 PU for a half cycle to 1 minute. As a result, the vast burdens and energization of the capacitor banks will be turned off, causing voltage swell [2,5-8].

IEEE and IEC have introduced the standards for Power Quality (PQ). There are many types of custom power devices that could be applied to mitigate voltage sag and

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